

6-2012

Maxwell's Equations, Part VII

David W. Ball

Cleveland State University, d.ball@csuohio.edu

Follow this and additional works at: https://engagedscholarship.csuohio.edu/scichem_facpub



Part of the [Physical Chemistry Commons](#)

How does access to this work benefit you? Let us know!

Recommended Citation

Ball, David W. (2012). Maxwell's Equations, Part VII. *Spectroscopy*, 27(6), 20-27.

This Article is brought to you for free and open access by the Chemistry Department at EngagedScholarship@CSU. It has been accepted for inclusion in Chemistry Faculty Publications by an authorized administrator of EngagedScholarship@CSU. For more information, please contact library.es@csuohio.edu.

Maxwell's Equations, Part VII

This is the seventh (and perhaps last) installment of a series of columns on Maxwell's equations of electrodynamics. In previous columns (available at Spectroscopy's website, www.spectroscopyonline.com/The+Baseline+Column), we have covered history, the background of the first three equations, and the mathematics underlying them. Here we will present the fourth equation, and after reaching it we'll see how light is described in terms of these four mathematical expressions.

David W. Ball

Ampère's law

One of the giants in the development of the modern understanding of electricity and magnetism was the French scientist André-Marie Ampère (1775 – 1836). He was one of the first to demonstrate conclusively that electrical current generated magnetic fields. (1 – 3) For a straight wire, Ampere demonstrated that the magnetic field's effects were centered on the wire carrying the current, were perpendicular to the wire, and were symmetric about the wire. This is illustrated in Figure 42.

This Figure is strangely reminiscent of Figure 37 of part V of this series, reproduced here as Figure 43. It depicts water circulating around a drain in a counterclockwise fashion. But now, let's put a paddle wheel in the drain, with its axis sticking in the drain as shown in Figure 44. We see that the paddle wheel will rotate about an axis that is perpendicular to the plane of

flow of the water. Rotate our water-and-paddle-wheel figure by 90 degrees counterclockwise, and you have an exact analogy to Figure 42.

We argued in the last two installations (3,4) that water circulating in sink as shown in Figures 42 and 43 represent a function that has a nonzero curl. Recall that the curl of a vector function \mathbf{F} , designated “curl \mathbf{F} ” or “ $\nabla \times \mathbf{F}$ ” is defined as

$$\text{curl } \mathbf{F} = \nabla \times \mathbf{F} = \left[\frac{\delta F_z}{\delta y} - \frac{\delta F_y}{\delta z} \right] \mathbf{i} + \left[\frac{\delta F_x}{\delta z} - \frac{\delta F_z}{\delta x} \right] \mathbf{j} + \left[\frac{\delta F_y}{\delta x} - \frac{\delta F_x}{\delta y} \right] \mathbf{k}$$

where F_x , F_y , and F_z are the x , y , and z magnitudes of \mathbf{F} and \mathbf{i} , \mathbf{j} , and \mathbf{k} are the unit vectors in the x , y , and z dimensions, respectively. In admitting the similarity between Figures 42 and 43, we suggest that the curl of the magnetic field, \mathbf{B} , is related to the current in the straight wire. There is a formal way to derive this. Recall from equation 6 in the previous installment (4) that the curl of a function \mathbf{F} as

$$\text{curl } \mathbf{F} = \nabla \times \mathbf{F} = \lim_{A \rightarrow 0} \frac{1}{A} \oint_S \mathbf{E} \cdot \mathbf{t} \, ds$$

For the curl of the magnetic field, we thus have

$$\nabla \times \mathbf{B} = \lim_{A \rightarrow 0} \frac{1}{A} \oint_S \mathbf{B} \cdot \mathbf{t} \, ds$$

Recall that S is the surface about which the line s is tracing, \mathbf{t} is the tangent vector on the field line, and A is the area of the surface.

This simplifies easily when one remembers that we have a formula for \mathbf{B} in terms of the distance from the wire r ; it was presented in part V and is

$$\mathbf{B} = \frac{\mu I}{2\pi r}$$

where I is the current, r is the radial distance from the wire, and μ is the constant known as the permeability of the medium; for vacuum, the symbol μ_0 is used and its value is defined as

$4\pi \times 10^{-7}$ tesla-meters per ampere (T·m/A)/ We also know that the magnetic field paths are circles: thus, as we integrate about the surface, the integral over ds becomes simply the circumference of a surface, $2\pi r$. Substituting these expressions into the curl of \mathbf{B} :

$$\nabla \times \mathbf{B} = \lim_{A \rightarrow 0} \frac{1}{A} \frac{\mu I}{2\pi r} (2\pi r)$$

The $2\pi r$ terms cancel; we are left with

$$\nabla \times \mathbf{B} = \lim_{A \rightarrow 0} \frac{\mu I}{A}$$

The constant μ can be taken out of the limit. What we have left to interpret is

$$\lim_{A \rightarrow 0} \frac{I}{A}$$

This is the limit of the current I flowing through an area A of the wire as the area gets smaller and smaller, ultimately approaching zero. This infinitesimal current per area is called the current density and is designated J ; it has units of coulombs per square meter, or C/m². Since current is technically a vector, so is current density: \mathbf{J} . Thus, we have

$$\nabla \times \mathbf{B} = \mu \mathbf{J}$$

This expression is known as Ampère's circuital law. In a vacuum, the expression becomes

$$\nabla \times \mathbf{B} = \mu_0 \mathbf{J}$$

This is not one of Maxwell's equations; it is incomplete. It turns out that there is another source of a magnetic field.

Maxwell's displacement current

The basis of Ampère's circuital law was discovered in 1826 (although its modern mathematical formulation came over 35 years later). By the time Maxwell got around to

studying electromagnetic phenomena in the 1860s, something new had been discovered: magnetic fields from capacitors.

Here's how to think of this new development. A capacitor is a device that stores electrical charge. The earliest form of capacitor was the Leyden jar, described in part I of this series, (2) and a picture of which is shown in Figure 45. Although the engineering of modern capacitors can vary, a simple capacitor can be thought of as two parallel metal plates separated by a vacuum or some other nonconductor, called a dielectric. Figure 46 shows a diagram of a parallel-plate capacitor.

A capacitor works because of the gap between the plates: in an electrical circuit, current enters a plate on one side of the capacitor. However, because of the gap between the plates, the current builds up on one side, ultimately causing an electric field to exist between the plates.. We know now that current is electrons, so in modern terms, electrons build up on one side of the plate. However, electrons have a negative charge, which repel other electrons residing on the other plate. These electrons get forced away, resulting in the other plate building up an overall positive charge. These electrons that get forced away represent a current on the other side of the plate, which continues until the maximum charge has built up on the other plate. This process is illustrated in Figure 47.

Even though electrons are not flowing from one side of the capacitor to the other, during the course of charging the capacitor, a current flows and generates a magnetic field. This magnetic field, caused by the changing electric field is not accounted for by Ampère's circuital law because it is the result of a *changing* electric field, not a constant current.

Maxwell was concerned about this new source of a magnetic field. He called this new type of current "displacement current" and set about to integrating it into Ampère's circuital law.

Because this magnetic field was proportional to the development of an electric field – that is, the change in \mathbf{E} with respect to time, we have

$$\nabla \times \mathbf{B} \propto \frac{\partial \mathbf{E}}{\partial t}$$

The proportionality constant needed to make this an equality is the permittivity of free space, symbolized ϵ_0 . This fundamental constant has a value of about $8.854 \times 10^{-12} \text{ C}^2/\text{J}\cdot\text{m}$. Since electric field has units of volts per meter, or V/m, the combined terms $\epsilon_0 \frac{\partial \mathbf{E}}{\partial t}$ have units of

$$\frac{\text{C}^2}{\text{J} \cdot \text{m}} \times \frac{\text{V}}{\text{m} \cdot \text{s}}$$

where the “s” unit comes from the δt in the derivative. A volt is equal to a joule/coulomb, and a coulomb/second is equal to an ampere, so the combined units reduce to

$$\frac{\text{A}}{\text{m}^2}$$

which is a unit of current density! Thus, we can add the term $\epsilon_0 \frac{\partial \mathbf{E}}{\partial t}$ to the original current density \mathbf{J} , yielding Maxwell’s fourth equation of electrodynamics:

$$\nabla \times \mathbf{B} = \mu_0 \left(\mathbf{J} + \epsilon_0 \frac{\partial \mathbf{E}}{\partial t} \right)$$

This equation is sometimes called the Ampère-Maxwell law.

Recap – The Four Equations

Maxwell’s four equations of electrodynamics are thus:

$$\nabla \cdot \mathbf{E} = \frac{\rho}{\epsilon_0} \quad \text{Gauss' law}$$

$$\nabla \cdot \mathbf{B} = 0 \quad \text{Gauss' law of electromagnetism}$$

$$\nabla \times \mathbf{E} = -\frac{\partial \mathbf{B}}{\partial t} \quad \text{Faraday's law}$$

$$\nabla \times \mathbf{B} = \mu_0 \left(\mathbf{J} + \varepsilon_0 \frac{\partial \mathbf{E}}{\partial t} \right) \quad \text{Ampère – Maxwell law}$$

A few comments are in order. First, Maxwell didn't actually present the four laws in this form in his original discourse. His original work, detailed in a four-part series of papers titled “On Physical Lines of Force” (5), contained dozens of equations. It remained to others, especially English scientist Oliver Heaviside, to reformulate Maxwell's derivations into four concise equations using modern terminology and symbolism. We owe almost as much a debt to the scientists who took over after Maxwell's untimely death in 1879 as we do to Maxwell himself for these equations.

Second, note that the four equations have expressed in differential forms. (Recall that the divergence and curl operations, $\nabla \cdot$ and $\nabla \times$ respectively, are defined in terms of derivatives.) There are other forms of Maxwell's equations, including integral forms, so-called “macroscopic” forms, relativistic forms, even forms that assume the existence of magnetic monopoles (likely only of interest to theoretical physicists and science fiction writers). The specific form you might want to use depends on the quantities you know, the boundary conditions of the problem, and what you want to predict. Persons interested in these other forms of Maxwell's equations are urged to consult the technical literature.

Whence Light?

We began this seven-part series by claiming that light itself is an electromagnetic effect that is predicted by Maxwell's equations. How? Actually, it comes from an analysis of Faraday's law and the Ampère-Maxwell law, as these are the two of Maxwell's equations that involve both \mathbf{E} and \mathbf{B} .

Among the theorems of vector calculus is the proof (not given here) that the curl of a curl of a function is related to the divergence. For a given vector function \mathbf{F} , the curl of the curl of \mathbf{F} is given by

$$\nabla \times (\nabla \times \mathbf{F}) = \nabla(\nabla \cdot \mathbf{F}) - \nabla^2 \mathbf{F}$$

Hopefully you already recognize the “ $\nabla \cdot \mathbf{F}$ ” as the divergence of the vector function \mathbf{F} . There is one other type of function present on the right side of the equation, the simple “ ∇ ” by itself (without a dot or a cross). Unadorned by the dot or cross, the ∇ represents something called the *gradient*, which is simply nothing more than the three-dimensional slope of a vector function, itself expressed as a vector in terms of the unit vectors \mathbf{i} , \mathbf{j} , and \mathbf{k} :

$$\nabla \mathbf{F} = \mathbf{i} \frac{\partial \mathbf{F}}{\partial x} + \mathbf{j} \frac{\partial \mathbf{F}}{\partial y} + \mathbf{k} \frac{\partial \mathbf{F}}{\partial z}$$

The first term on the right, then, is the gradient of the divergence of \mathbf{F} . The gradient can also be applied twice – that’s the last term on the right-hand side. When this happens, what initially seems complicated simplifies quite a bit:

$$\begin{aligned} \nabla^2 \mathbf{F} &= \left(\mathbf{i} \frac{\partial \mathbf{F}}{\partial x} + \mathbf{j} \frac{\partial \mathbf{F}}{\partial y} + \mathbf{k} \frac{\partial \mathbf{F}}{\partial z} \right) \left(\mathbf{i} \frac{\partial \mathbf{F}}{\partial x} + \mathbf{j} \frac{\partial \mathbf{F}}{\partial y} + \mathbf{k} \frac{\partial \mathbf{F}}{\partial z} \right) \\ \nabla^2 \mathbf{F} &= \frac{\partial^2 \mathbf{F}}{\partial^2 x} + \frac{\partial^2 \mathbf{F}}{\partial^2 y} + \frac{\partial^2 \mathbf{F}}{\partial^2 z} \end{aligned}$$

Note that there is now no \mathbf{i} , \mathbf{j} , or \mathbf{k} vectors on these terms, and that there are no cross terms between x , y , and z . This is because the \mathbf{i} , \mathbf{j} , and \mathbf{k} vectors are orthonormal: $\mathbf{n}_1 \cdot \mathbf{n}_2 = 1$ if \mathbf{n}_1 and \mathbf{n}_2 are the same (that is, both are \mathbf{i} or both are \mathbf{j}) while $\mathbf{n}_1 \cdot \mathbf{n}_2 = 0$ if \mathbf{n}_1 and \mathbf{n}_2 are different (for example, \mathbf{n}_1 represents \mathbf{i} and \mathbf{n}_2 represents \mathbf{k}).

What we do is take the curl of both sides of Faraday’s law:

$$\nabla \times (\nabla \times \mathbf{E}) = \nabla \times \left(-\frac{\partial \mathbf{B}}{\partial t} \right)$$

Because the curl is simply a group of spatial derivatives, it can be brought inside the derivative with respect to time on the right side of the equation:

$$\nabla \times (\nabla \times \mathbf{E}) = \left(-\frac{\partial(\nabla \times \mathbf{B})}{\partial t} \right)$$

and we can substitute the expression for what the curl of a curl is on the left side:

$$\nabla(\nabla \cdot \mathbf{E}) - \nabla^2 \mathbf{E} = \left(-\frac{\partial(\nabla \times \mathbf{B})}{\partial t} \right)$$

The expression “ $\nabla \times \mathbf{B}$ ” is defined by the Ampère-Maxwell law (Maxwell’s fourth equation), so we can substitute for $\nabla \times \mathbf{B}$:

$$\nabla(\nabla \cdot \mathbf{E}) - \nabla^2 \mathbf{E} = \left(-\frac{\partial(\mu_0 (\mathbf{J} + \epsilon_0 \frac{\partial \mathbf{E}}{\partial t}))}{\partial t} \right)$$

Faraday’s law (or Maxwell’s first equation) tells us what $\nabla \cdot \mathbf{E}$ is: it equals ρ/ϵ_0 . We substitute this in to the first term on the left side:

$$\nabla \left(\frac{\rho}{\epsilon_0} \right) - \nabla^2 \mathbf{E} = \left(-\frac{\partial(\mu_0 (\mathbf{J} + \epsilon_0 \frac{\partial \mathbf{E}}{\partial t}))}{\partial t} \right)$$

Now we will rewrite the right side by separating the two terms to get two derivatives with respect to time. Note that the second term becomes a second derivative with respect to time, and that μ_0 , the permeability of a vacuum, distributes through to both terms. We get

$$\nabla \left(\frac{\rho}{\epsilon_0} \right) - \nabla^2 \mathbf{E} = -\frac{\partial(\mu_0 \mathbf{J})}{\partial t} - \mu_0 \epsilon_0 \frac{\partial^2 \mathbf{E}}{\partial t^2}$$

In the absence of charge, $\rho = 0$, and in the absence of a current, $\mathbf{J} = 0$. Under these conditions, the first terms on both sides are zero, and the negative signs on the remaining terms cancel.

What remains is

$$\nabla^2 \mathbf{E} = \mu_0 \epsilon_0 \frac{\partial^2 \mathbf{E}}{\partial t^2}$$

This is a second-order differential equation that relates an electric field that varies in space and time. That is, it describes a *wave*, and this differential equation is known in physics as the *wave equation*. The general form of the wave equation is

$$\nabla^2 \mathbf{F} = \frac{1}{v^2} \frac{\partial^2 \mathbf{F}}{\partial t^2}$$

where v is the velocity of the wave. The function \mathbf{F} can be expressed in terms of sine and cosine functions or as an imaginary exponential function; the exact expression for an \mathbf{E} wave (aka light) depends on the boundary conditions and the initial value at some point in space.

The wave equation implies that

$$v_{\text{light}} = \frac{1}{\sqrt{\mu_0 \epsilon_0}}$$

This can be easily demonstrated:

$$\begin{aligned} v_{\text{light}} &= \frac{1}{\sqrt{\left(4\pi \times 10^{-7} \frac{\text{T} \cdot \text{m}}{\text{A}}\right) \left(8.8541878 \times 10^{-12} \frac{\text{C}^2}{\text{J} \cdot \text{m}}\right)}} \\ &= 2.9979246 \dots \times 10^8 \text{ m/s} \end{aligned}$$

(You have to decompose the telsa unit, T, into its fundamental units, $\text{kg}/\text{A} \cdot \text{s}^2$, to see how the units work out. Remember also that $\text{J} = \text{kg} \cdot \text{m}^2/\text{s}^2$ and that $\text{A} = \text{C}/\text{s}$ and everything works out naturally, as it should with units.) Even by the early 1860s, experimental determinations of the speed of light were around that value, leading Maxwell to conclude that light was a wave of an electric field that had a velocity of $(1/\mu_0 \epsilon_0)^{1/2}$.

Light is also a *magnetic* wave. How do we know? Because we can take the curl of the Ampère-Maxwell law and perform similar substitutions. This exercise is left to the reader, but the conclusion is not. Ultimate you will get

$$\nabla^2 \mathbf{B} = \mu_0 \epsilon_0 \frac{\partial^2 \mathbf{B}}{\partial t^2}$$

It is the same form of the wave equation, therefore we have the same conclusions: light is a wave of a magnetic field having a velocity of $(1/\mu_0 \epsilon_0)^{1/2}$. However, because of Faraday's law (Maxwell's third equation), the electric wave and the magnetic wave are perpendicular to each other. A modern depiction of what we now call electromagnetic waves is shown in Figure 48.

Conclusion

Along with the theory of gravity, laws of motion, and atomic theory, Maxwell's equations were triumphs of classical science. Although ultimately supplanted by theories of relativity (indeed, Einstein's seminal paper on special relativity was titled "On the Electrodynamics of Moving Bodies"), Maxwell's equations are still indispensable when dealing with everyday phenomena involving electricity and magnetism and, yes, light. They help us understand the natural universe better – after all, isn't that what good scientific models should do?

I hope the reader has enjoyed this series on Maxwell's equations. I would appreciate any feedback via the email address below.

Acknowledgements

Thanks to editor Laura Bush of *Spectroscopy* for letting me venture on such a long series on one topic. Thanks also to John Q. Buquoi of the US Air Force Academy, Department of Chemistry, for support.

References

1. B. Baigrie. *Electricity and Magnetism: A Historical Perspective* Greenwood Press: Westport, CT, 2007.
2. D. W. Ball. *Spectroscopy* **2011**, 26 (4), 16.
3. D. W. Ball. *Spectroscopy* **2012**, 27 (1), 24.
4. D. W. Ball. *Spectroscopy* **2012**, 27 (4), XX.
5. J. C. Maxwell. *Phil. Mag.* vol. 21 and 23, 1861 – 2.
6. In writing this series, I have been strongly influenced by the following works:
 - H. M. Schey. “Div, grad, curl, and all that: an informal text on vector calculus” W. W. Norton and Company: New York, 2005.
 - D. Fleisch. “A Student’s Guide to Maxwell’s Equations” Cambridge University Press: Cambridge, 2008.

Both books were very readable and insightful. I am grateful to both authors for producing books from which I could learn myself.

[AU's note: Use current author picture, but please use this new bio.]

David W. Ball is a professor of chemistry at Cleveland State University in Ohio. Many of his “Baseline” columns have been reprinted as *The Basics of Spectroscopy*, available through SPIE Press. Soon, this entire series of columns on Maxwell’s equations will be printed in book form as *Maxwell’s Equations of Electrodynamics: An Explanation*, also available through SPIE Press. Professor Ball sees spectroscopy from a physical chemistry perspective, because that’s his background. He recently served as Distinguished Visiting Professor at the US Air Force Academy, but is now back home in Ohio. He can be reached at d.ball@csuohio.edu.

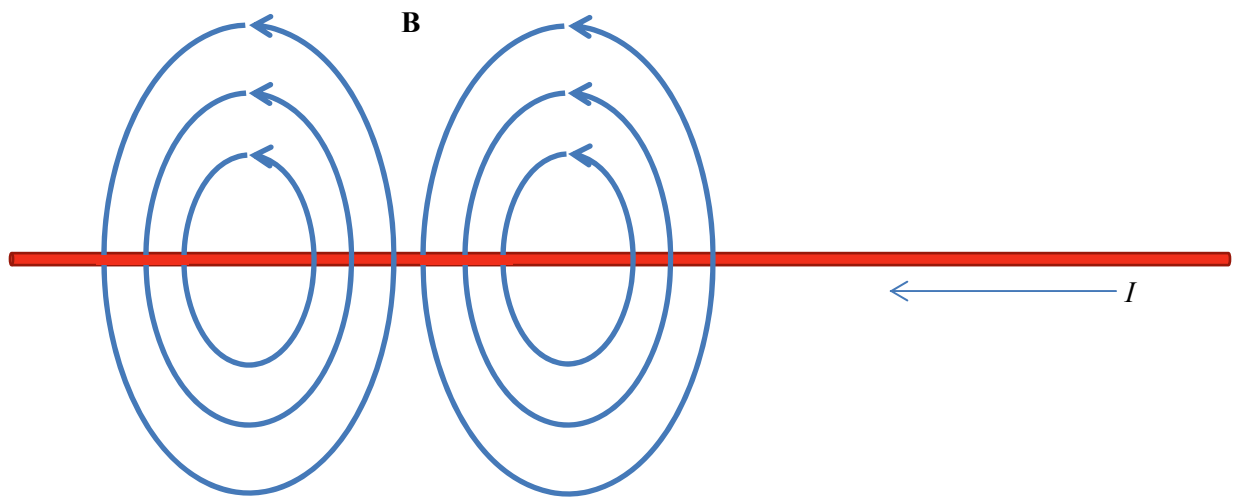


Figure 42. The “shape” of a magnetic field about a wire with a current running through it.

Reprinted from (3).

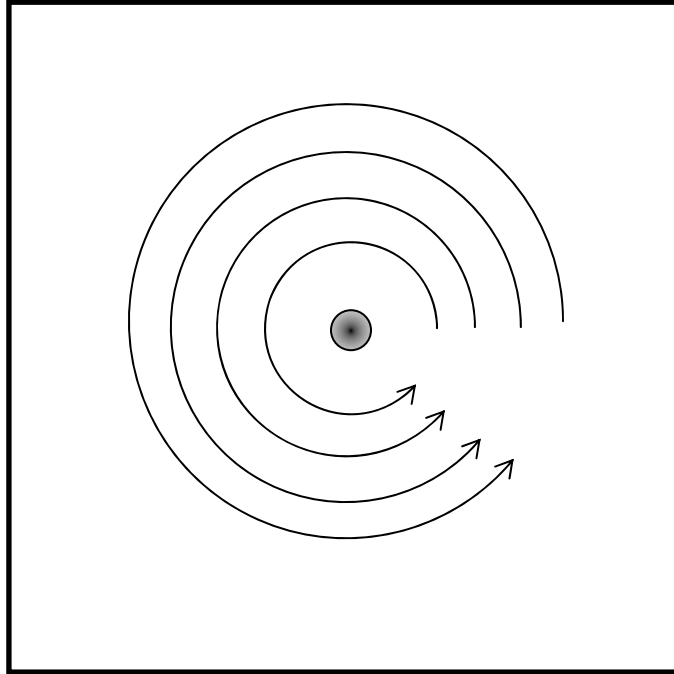


Figure 43. Water going in a circular path about a drain (center). Reprinted from (3).

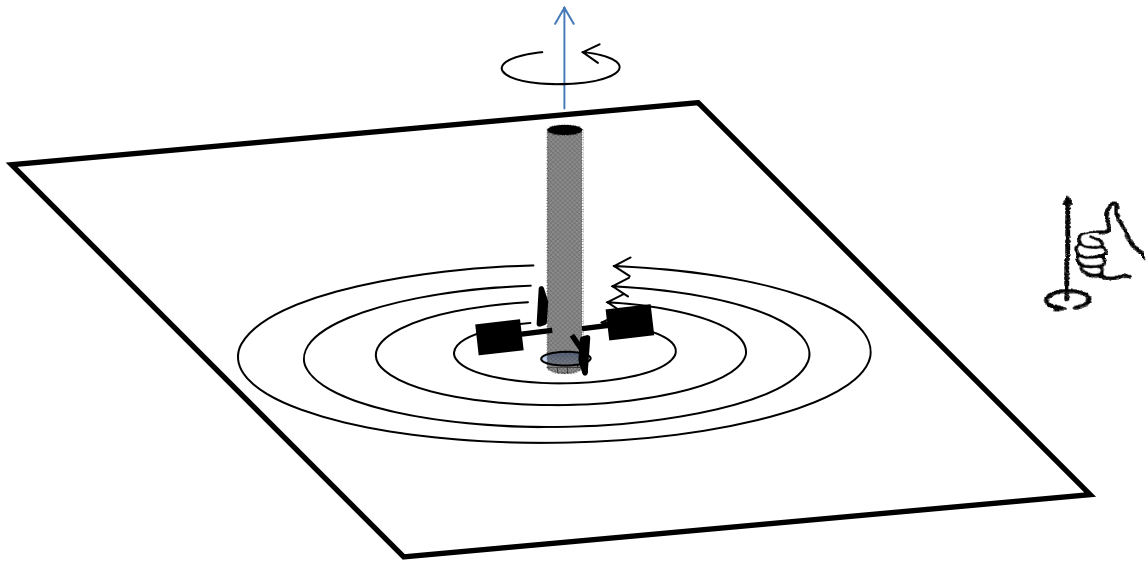


Figure 44. The paddle wheel rotates about a perpendicular axis when placed in the circularly-flowing water. We say that the water has a non-zero curl. The axis of the paddle wheel is consistent with the right hand rule, as shown by the inset.



Figure 45. A series of four Leyden jars in a museum in Leiden, The Netherlands. This type of jar was to be filled with water. The apparatus on the bottom side is a simple electrometer, meant to give an indication of how much charge was stored in these ancient capacitors.

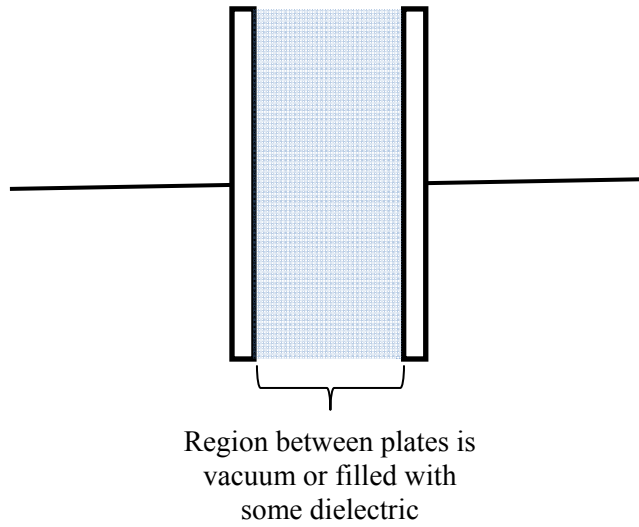


Figure 46. Diagram of a simple parallel-plate capacitor.

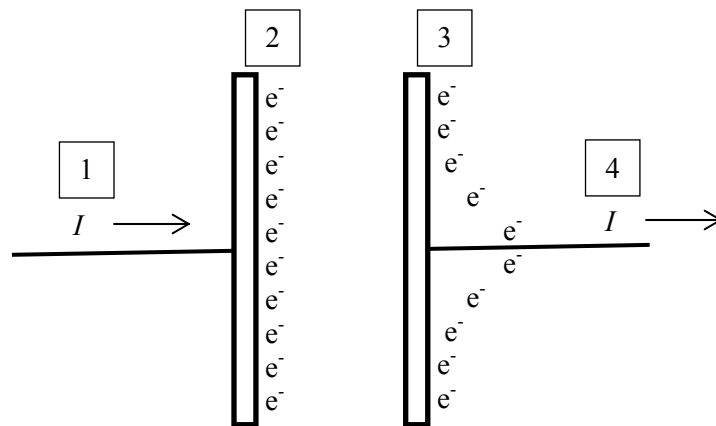


Figure 47. Charging a capacitor. (1) Current enters one plate. (2) Electrons build up on the plate. (3) Electrons on the other plate are repelled, causing (4) a short-lived current to leave the other plate.

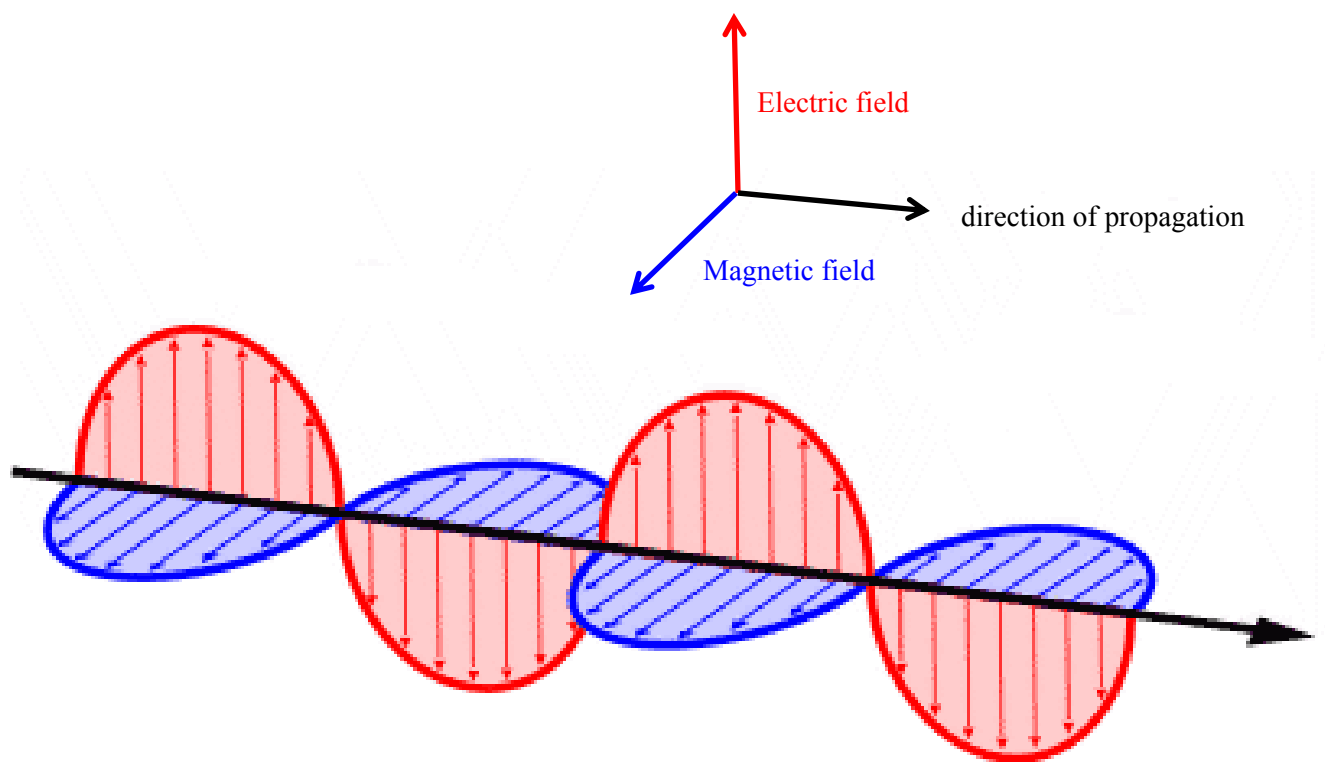


Figure 48. A modern depiction of the electromagnetic waves we know as light.