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1 Introduction

Polymer electrolyte membrane fuel cells (PEMFCs) are expected to become a prominent technology in a variety of energy generation applications, including stationary, portable, and automotive power sources. PEMFCs offer the potential advantages of high energy density, high efficiency, and clean operations, as well as providing the opportunity for greater energy security [1,2]. However, there are still a number of technical barriers that must be overcome before PEMFCs can realize their commercial potential. Probably the most challenging application for the PEMFC is in the transportation arena, where the fuel cell must displace the incumbent internal combustion engine technology. The higher temperature, and dryer operating conditions compared with stationary applications, combined with the need for robust performance in automotive duty cycle power transience imposes especially demanding requirements on the membrane electrode assembly (MEA) technology. The Department of Energy has outlined the durability targets for automotive fuel cells, which include 5000 h operational life over a full range of operation temperatures (−40°C to 120°C) [3].

A typical unit cell of a PEMFC is made of a membrane electrode assembly (MEA) sandwiched between two gas diffusion layers (GDL). These are in turn compressed on either side by bipolar plates, which are generally graphite or metallic plates with gas flow channels formed in them. The MEA is the core component of PEMFC and consists of an ion conducting polymer electrolyte membrane with electrodes attached to each side. In a typical fuel cell stack many unit cells will be stacked together in series and clamped between end-plates to obtain the desired voltage and power requirements.

There has been very little work published on the effects of automotive duty cycles upon the operational life of the components comprising the PEMFC unit cell. An automotive duty cycle is likely to not only impose rapid changes in the current density and voltage of the cell, but also result in changes in the cell temperature, pressure, reactant flow rates and relative humidity. As a result of the changes in temperature and moisture, the PEM, GDL and bipolar plates will all experience expansion and contraction. Because of the different thermal expansion and swelling coefficients between these materials, hygrothermal stresses are expected to be introduced into the unit cell during operation. In addition, the nonuniform current and reactant flow distributions in the cell may result in nonuniform temperature and moisture content of the cell [4] which could in turn, potentially causing localized increases in the stress magnitudes.

In use, the PEM must provide proton transport from anode to cathode, while acting as an electronic insulator and a gas barrier to prevent mixing of oxygen and hydrogen. Any discontinuity of the membrane will result in failure of the fuel cell. Several publications have reported the importance of the membranes mechanical properties on operational life. Mechanical failures in the MEA have been reported after thermal and hydration cycling during fuel cell service [5–7]. These failures can appear as pinholes in the membrane or delamination between the MEA and GDL [5,6]. Studies [7] show that hygrothermal stresses might be an important reason for such failure. Weber and Newman [7] pointed out that mechanical stresses may be particularly important in systems that are nonisothermal.

The need for improved lifetime of PEMFCs necessitates that the failure mechanisms be clearly understood and life prediction models be developed, so that new designs can be introduced to improve long-term performance. To the author’s knowledge, Weber and Newman’s paper [7] is the first to incorporate the effect of mechanical stresses into a fuel cell model. However, their model is one-dimensional and does not include the effects of material property mismatch among PEM, GDL, and bipolar plates. The goal of the current investigation is to study the hygro and thermal stresses in different fuel cell assembly structures as they interact under environments approaching realistic conditions.

2 Model Definition

In order to keep a tractable set of parameters, several simplifying assumptions have been made in the development of this preliminary finite element model (Table 1). Whereas the actual system is three-dimensional, our model to-date is two dimensional.
An operating fuel cell has varying local conditions of temperature, humidity, and power generation (and thereby heat generation) across the active area of the fuel cell [8–17]. In this preliminary model, a simplified temperature and humidity profile was assumed in order to demonstrate the effects these variables can have on the stress state of the system. An illustrative temperature profile has been estimated as follows: cathode/GDE (gas diffusion electrode) and anode/GDE interface temperatures of 86°C and 85°C, respectively, are fixed. These values are reasonable for a fuel cell operating at 80°C under typical conditions [18]. The bipolar plate is assumed to have a constant temperature at its midplane, and is set to the cell operating temperature of 80°C. The model then calculates the internal temperature distribution profile produced from these boundary conditions. The resulting temperature profile is shown in Fig. 1.

As a first approximation, and to reduce the computational complexity in the model, the humidity profile has been assumed uniform throughout the membrane. The initial relative humidity of the membrane is taken as 35%, and then increased to 100% to simulate operating conditions. Both temperature and relative humidity profiles are assumed to be constant in time and there are no internal heat-generation terms. Rather, stress generation arising from humidity and temperature changes have been modeled by applying step changes in temperature and relative humidity from the initial zero-stress state of room temperature, and 35% relative humidity. Furthermore, this initial model assumes only linear elastic response of all components, and uses the further simplifying assumption that all the materials have isotropic thermal and humidity expansion behavior (except when noted) that are uncoupled. Also, the catalyst is assumed to be integrated into the GDE instead of considering this as a separate layer. Each of these simplifying assumptions will be relaxed in future work.

Using hygrothermoelasticity theory, we address the effects of temperature and moisture as well as the mechanical forces on the behavior of elastic bodies. In the present study, we consider only the uncoupled theory for which the additional temperature changes brought about by the strain are neglected. Also, within the context of linearity we assume that the total strain tensor, $\varepsilon_{ij}$, is the sum

$$\varepsilon_{ij} = \varepsilon_{ij}^M + \varepsilon_{ij}^T + \varepsilon_{ij}^S$$

where, $\varepsilon_{ij}^M$ is the contribution from the mechanical forces and $\varepsilon_{ij}^T$, $\varepsilon_{ij}^S$ are the temperature and swelling induced strains, respectively.

If $T_0$ is taken as a reference temperature and $T$ as the actual temperature, the thermal strains resulting from a change in temperature of a completely unconstrained isotropic volume are given by

$$\varepsilon_{ij}^T = \alpha(T - T_0)\delta_{ij}$$

$\alpha$ is the linear coefficient of thermal expansion, having units of $m \cdot m^{-1} \cdot K^{-1}$. $\delta_{ij}$ is the Kronecker symbol. Similarly, the swelling strains caused by moisture change are given by

$$\varepsilon_{ij}^S = \beta_{ij}(C - C_0)$$

where $\beta_{ij}$ is the swelling coefficient tensor due to moisture absorption; when the material is isotropic, $\beta_{ij} = \beta \delta_{ij}$. The swelling

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**Table 1 Model assumptions**

<table>
<thead>
<tr>
<th>Initial model parameters</th>
<th>Actual fuel cell</th>
<th>Future work</th>
</tr>
</thead>
<tbody>
<tr>
<td>2D</td>
<td>3D</td>
<td></td>
</tr>
<tr>
<td>No internal heat generation</td>
<td>Resistive, reaction and strain induced heat generated in cell</td>
<td>3D Provide internal heat-source term</td>
</tr>
<tr>
<td>Simplified temperature and humidity profile</td>
<td>Varying $T$ and humidity across active area</td>
<td>Vary $T$ and humidity and heat generation across an active area</td>
</tr>
<tr>
<td>Electrode layer not considered separately from GDL</td>
<td>Electrode layer separate and distinct from gas diffusion layer</td>
<td>Include separate electrode layer</td>
</tr>
<tr>
<td>Step-changes of $T$ and humidity</td>
<td>$T$ and humidity changes controlled by operating conditions so vary continually and nonuniformly across an active area in all three dimensions</td>
<td>Couple $T$ and humidity changes based on heat generation term</td>
</tr>
<tr>
<td>Temperature and humidity are independent and uncoupled</td>
<td>$T$ and humidity are coupled</td>
<td>Couple $T$ and humidity as determined from experimental data</td>
</tr>
<tr>
<td>Isotropic material parameters</td>
<td>Nonisotropic material behavior</td>
<td>Use experimentally measured nonisotropic behavior of key internal materials</td>
</tr>
<tr>
<td>Linear-elastic behavior of all components</td>
<td>Viscoelastic-viscoplastic response</td>
<td>Use elastic-plastic response as function of $T$ and humidity for key internal materials</td>
</tr>
</tbody>
</table>

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**Fig. 1** The calculated temperature profile inside the unit fuel cell assuming a constant anode/GDE temperature of 85°C and cathode/GDE temperature of 86°C.
The mechanical boundary conditions are noted in the figure. In addition, two additional boundary conditions (not shown) for case (a) and (b) were imposed by subjecting the stack to either constant displacement or constant load clamping at the top.

Coefficient is usually defined as the relative change in length per 1% weight gain. Since, in the current application, relative humidity rather than water gain is assumed to be known as the swelling coefficient it is defined as the relative change in length per 1% relative humidity change. Then the units of $\beta$ are m/m/(% humidity change). $C$ is the relative humidity, and $C_0$ is the reference value for C.

From Hooke’s Law and Eqs. (1)–(3), we have the hygrothermoelastic constitutive equation

$$e_{ij} = \frac{1 + \nu}{E} \sigma_{ij} - \frac{\nu}{E} \delta_{ij} \sigma_{kk} + \alpha \Delta T \delta_{ij} + \beta_j \Delta C$$

where $\sigma_{kk} = \sigma_{11} + \sigma_{22} + \sigma_{33}$. Alternatively, expressing the stresses in terms of strain, we have,

$$\sigma_{ij} = \frac{E}{(1 + \nu)(1 - 2\nu)} \left[ \nu \delta_{ij} e_{kk} + (1 - 2\nu) e_{ij} - (1 + \nu) \alpha \Delta T \delta_{ij} - (\nu + 1) \beta_j \Delta C \right]$$

where $e_{kk} = e_{11} + e_{22} + e_{33}$.

In our current study, the generalized plane strain condition is assumed. In this case, Eqs. (4) and (5) can be simplified by applying conditions

$$e_{13} = e_{31} = e_{23} = e_{32} = 0 \quad \text{and} \quad e_{33} = \text{constant}$$

A schematic drawing of a PEMFC unit cell is shown in Fig. 2. Two different graphite plate alignments are selected to study the effects of geometry of the flow field assembly. In both cases, the thickness of the plates is taken as 11 mm. The depth and the width of grooves in the plate are 1 mm. To investigate the effects of membrane thickness, three different membrane thicknesses are used: 25 $\mu$m, 50 $\mu$m, and 100 $\mu$m. As mentioned previously, the catalyst layer is included in the gas diffusion layer, forming a gas diffusion electrode (GDE). In this model, the thickness of GDE is 100 $\mu$m.

The material properties used in this model are shown in Table 2. Two properties for the graphite plates are taken from commercial graphite, the carbon paper from TORAY® TGF-H-030 [19], and the membrane properties are from NAFION® [20]. From our ongoing research, the dimensional change of NAFION® from 35% to 100% relative humidity at 85°C is approximately 15%.

The units of $\beta$ we used in the model are mm/mm per percent relative humidity change, giving the swelling coefficient for NAFION® as 2300 (10⁻⁶ mm/mm per percent relative humidity change) [21].

Finite element models have been built for these different geometries, utilizing the commercial software, ABAQUS 6.4 [23]. A unit cell is selected from the assembly for analysis (as shown in Fig. 2). The boundary condition $u_2=0$ is applied on the bottom, and $u_1=0$ on the left-hand side, where $u_1$ is the deformation in the i direction. A linear constraint $A_i \mu_1^{N_i} + A_i \mu_2^{N_i} = 0$ is applied on the right side. For our problem, $A_1=1$ and $A_2=-1$ and $N_1$ and $N_2$ are node sets on the right-hand side. This condition constrains the right-hand side to displace uniformly. Four-node generalized plane strain temperature-displacement coupled elements CPE4T are used in the FE analysis.

ABAQUS does not have a built-in module for moisture expansion. Instead, the subroutine UEXPAN [23] is used to define the strain from thermal expansion and swelling (both isotropic and anisotropic cases). UEXPAN outputs an eigenstrain based on the state of defined field variables. In the present case, humidity and temperature, along with their changes, are used as input to UEXPAN. The routine calculates the expansion caused by both the change in temperature and humidity.

The channels in the graphite plates are used for gas transport to and from the membrane. Typically, hydrogen is brought to the anode side of the MEA and air to the cathode, while water vapor is carried away. In some cases, the channels on either side of the MEA are aligned with each other, in other cases they are not. Thus, two plate alignments are investigated (see Fig. 2) to compare their effects on the stresses in the membranes. The cases where the grooves are aligned will be referred to as “aligned” and the nonaligned cases as “alternating.” Our previous study [21] showed that the magnitudes of the stresses in the membrane are much higher than that in GDEs or the plates. Also, the mismatches in the thermal and swelling coefficients lead to compression in the membrane and bending in the GDE. This bending is especially pronounced in the alternating model.

Two different clamping methods are also investigated. The first method is fixed load, in which a constant pressure (1 MPa) is applied on the surface of the upper graphite plate; the second method is fixed displacement where the graphite plates are clamped, resulting in a net displacement in the thickness direction. In the fixed displacement models, the applied displacement is calculated by applying a 1 MPa load to an otherwise unloaded model. The applied displacements for the various models are shown in Table 3.
Table 3  Applied displacements used in the fixed displacement models

<table>
<thead>
<tr>
<th>Model</th>
<th>Thickness of membrane (μm)</th>
<th>Displacement (μm)</th>
</tr>
</thead>
<tbody>
<tr>
<td>Aligned</td>
<td>25</td>
<td>−2.669</td>
</tr>
<tr>
<td></td>
<td>50</td>
<td>−2.813</td>
</tr>
<tr>
<td></td>
<td>100</td>
<td>−3.094</td>
</tr>
<tr>
<td>Alternating</td>
<td>25</td>
<td>−3.310</td>
</tr>
<tr>
<td></td>
<td>50</td>
<td>−3.570</td>
</tr>
<tr>
<td></td>
<td>100</td>
<td>−3.982</td>
</tr>
</tbody>
</table>

3 Results and Discussions

3.1 Effects of Plate Alignments and Clamping Methods. Figure 1 illustrates the temperature profile inside the fuel cell unit cell. Figures 3–5 show the distribution of the in-plane stress $\sigma_{xx}$, out-plane stress $\sigma_{zz}$, and shear stress $\sigma_{xz}$, respectively, for the case of membrane thickness 50 μm and fixed loading. The directions $x$, $y$, and $z$ (Figs. 3–5) correspond to directions 1, 3, and 2 in Eqs. (1)–(6), respectively. In the finite element analysis, the initial relative humidity of the membrane is 35%, and then increased to 100% to simulate operating condition. Both temperature and humidity profiles are assumed to be constant in time. These results show that the in-plane stress $\sigma_{xx}$ is the dominant stress in the membrane, and the shear stress is quite small compared to in-plane and out-of-plane stresses. The different gas channel alignments also effect the stresses distributions. Figure 6 illustrates the stress distributions along the upper surface of the membrane as a function of the in-plane dimension “x.” It is clear that the stresses (both $\sigma_{xx}$ and $\sigma_{zz}$) have the highest magnitudes in the middle of the unit cell in an alternating model, and along the edge in an aligned model. Fixed displacement clamping introduces much larger stresses in the membrane than fixed load clamping. Although the magnitudes of the differences in the stress distributions are not large, they can induce localized bending stresses, which can contribute to failure of the system.

3.2 Effect of Membrane Thickness. We also studied the influence of the membrane thickness on the stresses, assuming all other parameters remain unchanged. Figures 7–9 show that if the plates are subjected to a fixed load, changing the thickness of the
membrane has a minor effect on \( \sigma_{xy} \), but \( \sigma_{xz} \) decreases as the thickness of the membrane increases in the alternating model. However, in the aligned model, \( \sigma_{xz} \) increases as the membrane thickness increases. If the plates are subjected to fixed displacement, all stresses increase with the increase of the membrane thickness, no matter if the gas channel is aligned or alternating.

### 3.3 Investigation of Anisotropy of the Membrane

Five different anisotropic cases of the membrane are investigated (Table 4). Hygrothermal stresses in the membrane (50 \( \mu \)m) under fixed displacement boundary condition are shown in Figures 10 and 11. It is obvious that the highest stresses occur in isotropic membranes. Most significant anisotropy effects in the membrane are on in-plane stress \( \sigma_{xx} \).

| Swelling (% length change from 35% to 100% relative humidity) |
|-----------------|-----------------|-----------------|-----------------|-----------------|-----------------|
| \( x \) direction | 15              | 5               | 5               | 0               | 0               |
| \( y \) direction | 15              | 5               | 0               | 5               | 0               |
| \( z \) direction | 15              | 15              | 15              | 15              | 15              |
4 Conclusions

The finite element method is used to investigate the hygrothermal stresses in fuel cell unit cell assemblies caused by temperature and relative humidity changes. The analysis shows that the in-plane stress is the dominant stress in the membrane. Nonuniform distribution of stresses, caused by the temperature gradient in the MEA, induces localized bending stresses, which can contribute to delamination between the membrane and the GDE. Comparison of the results for aligned and alternating alignment of the bipolar plates shows that the alignment of the gas channels affects the stresses distributions. In general, aligned gas channels produce smaller hygrothermal stresses than alternating channels. This analysis shows that fixed displacement fuel cell assemblies introduce larger stresses in the membrane than fixed load assemblies. Influence of membrane thickness is also studied, which shows a less significant effect. Isotropic membranes introduce the highest stresses in the membrane, and the most significant anisotropy effects in the membrane are on in-plane stress.

Acknowledgment

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References